

六轴机器人系统-喷涂工艺包说明书

深圳市华成工业控制股份有限公司

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前言

R6

()

R6



AO	2020-11	



1	1
1.1	1
1.2	1
1.3	1
1.4	1
1.5	2
2	3
2.1	3
2.2	3
3	4
3.1	4
3.2	6
3.2.1	6
3.2.2	7
3.2.3	7
3.2.4	8
3.2.5	8
3.2.6	9
4	9
4.1	9
4.2	10



1

2

3

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1)

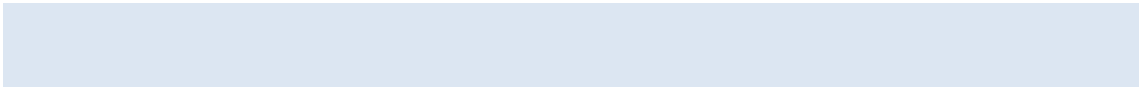
2)

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6)



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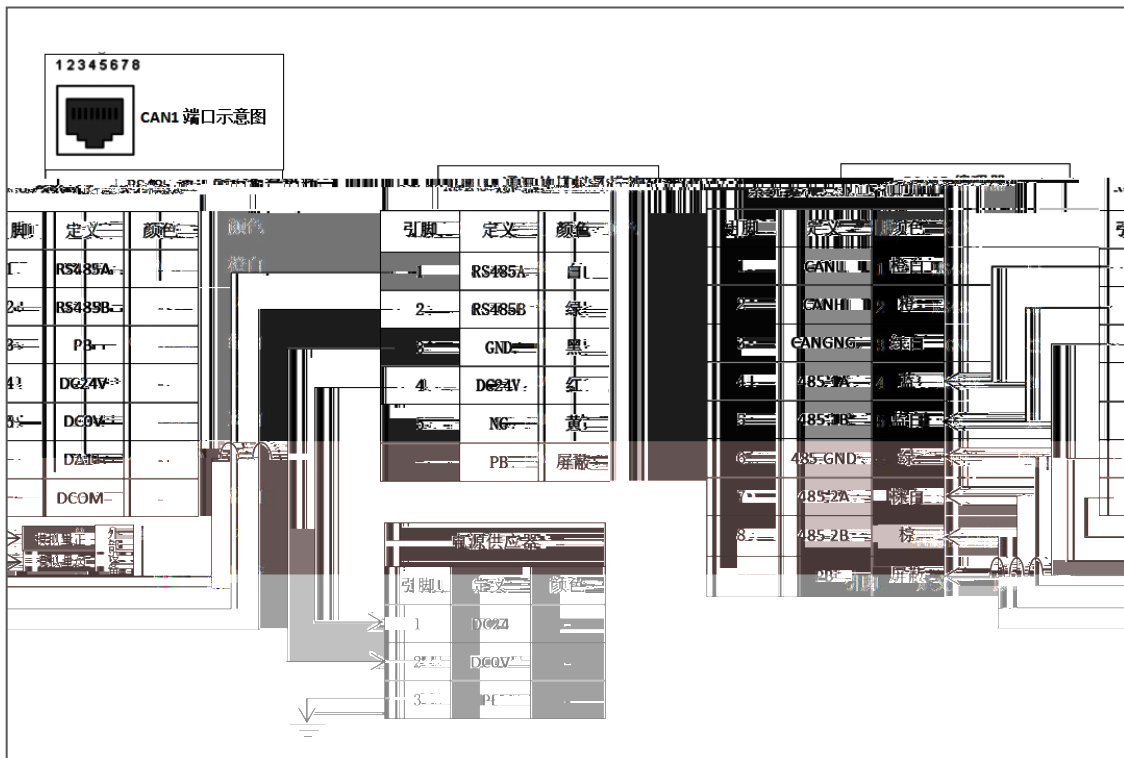
50

8)

1. 2.0.2.1, 7.8.01 ()
2. -> -> ()
3. -> RS485 ()
4. -> RS485 2.2 ()
5. -> RS485 RS485 ()
6. -> RS485 2.2 ()
7. ()
8. 7,8 ()

CAN/

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CANV



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1.

2.

3. Pn

4. Pn Pn

5. Pn

1 P1

2 Pn 32

6.

7.





- 1
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- 3
- 4
- 8.

0-10.0V

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输出点	延时(s)	添加	确定
Y 10	0	<input type="button" value="添加"/> <input type="button" value="删除"/> <input type="button" value="刷新"/>	

- 1
- 2
- 3
- 4
- 9.
- 10.

Y

Y10

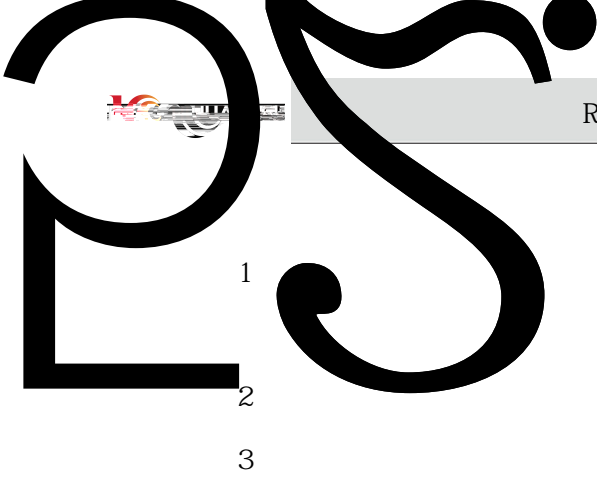
0

请选择插入的模块

插入到现有模块
 新建模块

请新建一个模块

模块名称:



11.

插入	调用模块	<input type="text"/>
	返回标签	<input type="text"/>
动作 → 菜单		

12.

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1. P1 P1->P2 P2 P2->P1 P1
2. P1-P2 P1-P2 P2-P1

3.2.2



1. P1 P1->P3 P3 P3->P1 P1
2. P1-P2-P3 P1-P2-P3 P3-P2-P1

3.2.3





1. P1 P1->P2 P2 P2->P1 P1 P3

2 n

3.2.4



1. P1 P1->P3 P3 P3->P1 P1 P2 P4

2 n

3.2.5



1. P1 P1->P2 P2 P2->P1 P1 P3

2 n



- 3 0 1
- 4
- 5

3.2.6



- 1. P1 P1->P3 P3 P3->P1 P1 P2 P4
- 2 n
- 3 0 1
- 4
- 5

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Q:      :      :0      :0      :0|5.00      :rev      :9      :3
P1:759.704|103.042|1359.972|-62.272|21.089|-32.330 P1      :10.0
P2:760.023|100.661|1359.972|-62.272|21.089|-32.509 P2      :20.0
P3:761.561|100.656|1354.616|-62.504|21.430|-32.593 P3      :30.0
P4:514.000|0.000|865.000|0.000|90.000|0.000 P4      :10.0
      :2P1      :0P2      :0P3      :0P4      :1

```



P1J:0.000|0.000|12.932|-66.558|45.860|16.566 P2J:-0.179|0.000|12.932|-66.558|45.860|16.566

P3J:-0.179|0.000|12.528|-66.558|45.860|16.566 P4J:0.000|0.000|0.000|0.000|0.000|0.000

IO:5|0.0 :1 :10.0 :0

1: : :J1:0.000,J2:0.000,J3:12.932,J4:-66.558,J5:45.860,J6:16.566

:10 :0.00 :

2: -0 :5.00 :0.0

3: :Y015 :0.0

4: : :X760.023,Y100.661,Z1359.972,U:-62.272,V:21.089,W:-32.509

:20 :0.00 :9

5: : :X760.217,Y103.040,Z1358.187,U:-62.272,V:21.089,W:-32.330

:10 :0.00 :9

6: : :X760.536,Y100.659,Z1358.187,U:-62.272,V:21.089,W:-32.509

:20 :0.00 :9

7: : :X760.729,Y103.039,Z1356.401,U:-62.272,V:21.089,W:-32.330

:10 :0.00 :9

8: : :X761.048,Y100.658,Z1356.401,U:-62.272,V:21.089,W:-32.509

:20 :0.00 :9

9: : :X761.242,Y103.037,Z1354.616,U:-62.272,V:21.089,W:-32.330

:10 :0.00 :9

10: : :X761.561,Y100.656,Z1354.616,U:-62.272,V:21.089,W:-32.509

:20 :0.00 :

11: :Y015 :0.0

12:

1.

2 8



3

4

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1

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0: : :J1:0,J2:0,J3:0,J4:0,J5:-90.000,J6:0

:80.0 :0.00 :

1: :[ID1]

2: : : + :0 :200.000 :0.000 :20.0

3: [2]:

4: : : +

5: :[ID0]

6:

[2]:

0: : :0 :0 :0| 1.00 :rev :9 :3

P1:759.704| 103.042| 1359.972| -62.272| 21.089| -32.330 P1 :10.0

P2:760.023| 100.661| 1359.972| -62.272| 21.089| -32.509 P2 :20.0

P3:761.561| 100.656| 1354.616| -62.504| 21.430| -32.593 P3 :30.0

P4:514.000|0.000| 865.000|0.000| 90.000|0.000 P4 :10.0

:2 P1 :0 P2 :0 P3 :0 P4 :1

P1J:0.000|0.000| 12.932| -66.558| 45.860| 16.566 P2J:-0.179|0.000| 12.932| -66.558| 45.860| 16.566

P3J:-0.179|0.000| 12.528| -66.558| 45.860| 16.566 P4J:0.000|0.000|0.000|0.000|0.000|0.000

IO:5|0.0 :1 :10.0 :0

1: : :J1:0.000,J2:0.000,J3:12.932,J4:-66.558,J5:45.860,J6:16.566

:10 :0.00 :

2: -0: :1.00 :0.0

3: :Y015 :0.0

4: : :X760.023,Y100.661,Z1359.972,U:-62.272,V:21.089,W:-32.509

:20 :0.00 :9

5: : :X760.217,Y103.040,Z1358.187,U:-62.272,V:21.089,W:-32.330

:10 :0.00 :9

6: : :X760.536,Y100.659,Z1358.187,U:-62.272,V:21.089,W:-32.509

:20 :0.00 :9

7: : :X760.729,Y103.039,Z1356.401,U:-62.272,V:21.089,W:-32.330

:10 :0.00 :9

8: : :X761.048,Y100.658,Z1356.401,U:-62.272,V:21.089,W:-32.509

:20 :0.00 :9

9: : :X761.242,Y103.037,Z1354.616,U:-62.272,V:21.089,W:-32.330

:10 :0.00 :9

10: : :X761.561,Y100.656,Z1354.616,U:-62.272,V:21.089,W:-32.509

:20 :0.00 :

11: :Y015 :0.0



12:

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0: :X014

1: : : +

X756.221,Y94.684,Z:1356.886

2: :1.0s

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0755-26417678

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